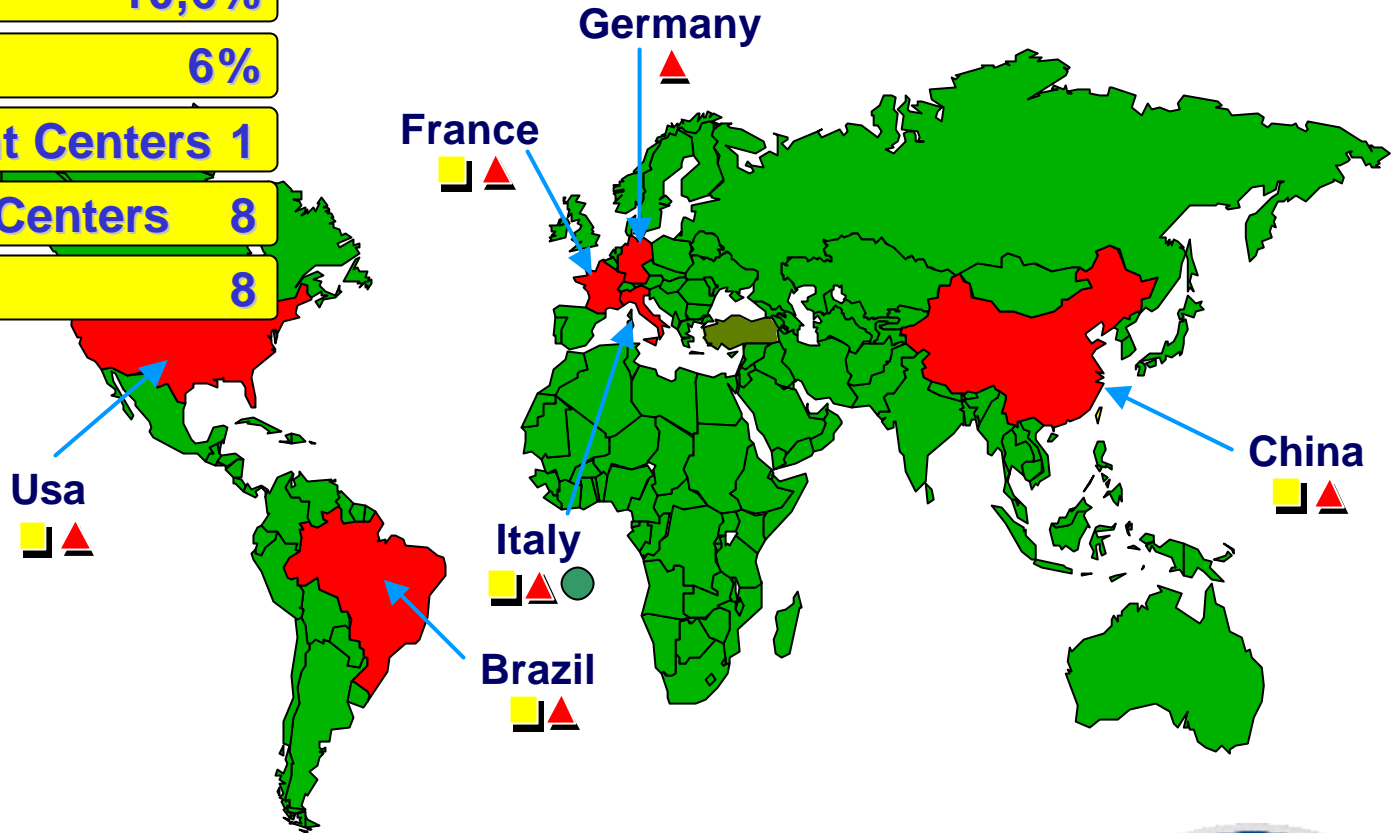




**Collaborazione MM-Università  
2005**

# WORLDWIDE PRESENCE

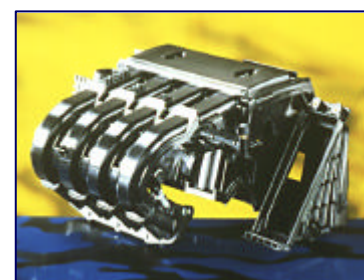
2003 Sales	€42 mln
Employees	4180
R&D	10,6%
Investments	6%
Development Centers	1
Application Centers	8
Plants	8



# MAIN PRODUCTS AND TECHNOLOGIES

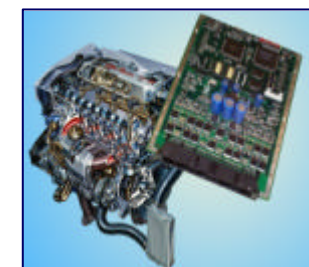
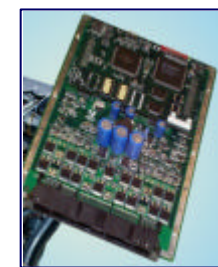
## Gasoline Engine Control

- ▶ ECUs
- ▶ Injectors
- ▶ Throttle bodies
- ▶ Intake manifolds
- ▶ Fuel rails



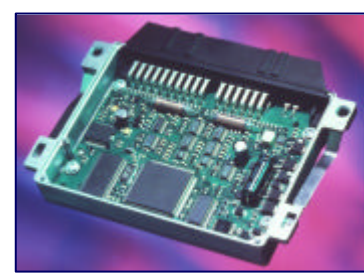
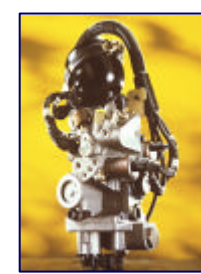
## Diesel Engine Control

- ▶ ECUs
- ▶ System components (buy)



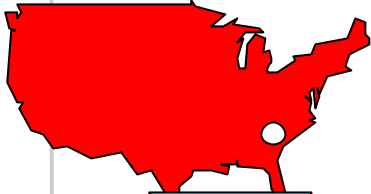
## Semi-automatic transmission

- ▶ Selespeed:
  - hydraulic power units
  - ECUs



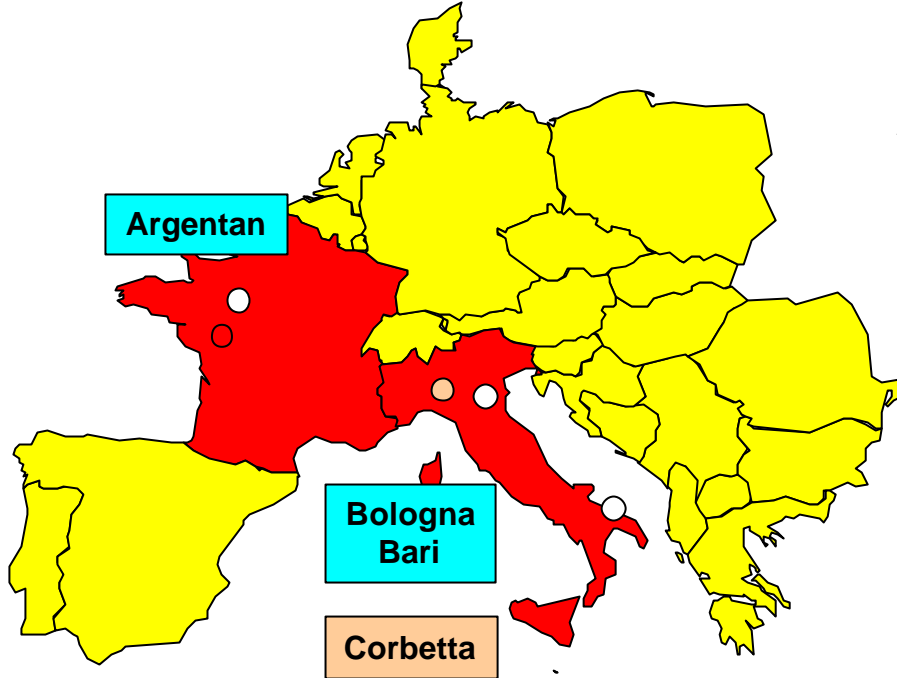
# PLANTS LOCATION

USA



Sanford

Europe



Argentan

Bologna  
Bari

Corbetta

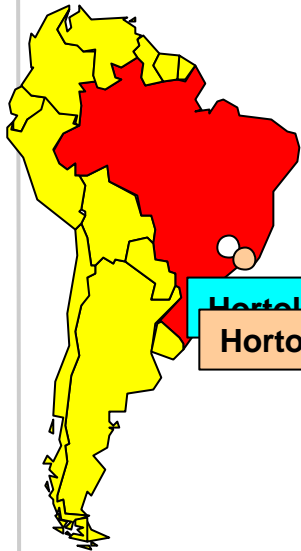
China



Shanghai  
Wuwu

Chinese partn  
(12 -2002)

South America



Hortolandia  
Hortolandia



# MARKET POSITION

## NAFTA

2003 turnover: €102 mio

Presence in niche market  
with high profitability

Clients: DC, GM,  
Harley Davidson

## Europe

2003 turnover: € 498 mio

Market share: 10% (PWT) #3  
(AMT) #2

Clients: Fiat, VW, RSA, PSA, DC,  
GM, BMW, Piaggio, Ducati

## China

2003 turnover: €55 mio

Market share: 6% (PWT)

Clients: Jinbei, Chery, SVW,  
DCAC, Nania  
and others

## Mercosur

2003 turnover: €87 mio

Market share: 39% (PWT) #1

Clients: Fiat, VW, GM, RSA, DC,  
PSA, Ford



## Electronic Components

- ▶ **Manufacturing plants in three continents (Europe, South America, Asia):**
  - **state of the art technology**
  - **highest level of quality certification**
- ▶ **Gamma products worldwide with localised industrial plants**
- ▶ **Investments:**
  - **flexibility**
  - **capacity/capability in multiple locations**
  - **capacity saturation worldwide**



# CURRENT ELECTRONIC PRODUCTS

	Europe	Brazil	China
▶ Gasoline Engine Control	✓	✓	✓
▶ Diesel Engine Control	✓		
▶ Transmission Control	✓		



# PLANTS DESCRIPTION

## Corbetta (Italy)

<b>Area</b>	6,000 m <sup>2</sup>
<b>Headcount</b>	
<b>Direct labour</b>	251
<b>Total</b>	345
<b>Certifications</b>	ISO 9001
<b>Products</b>	<ul style="list-style-type: none"><li>▶ SPI, MPI Control unit</li><li>▶ DBW Control unit</li><li>▶ Selespeed Control unit</li></ul>
<b>Technologies</b>	<ul style="list-style-type: none"><li>▶ PCB process</li><li>▶ Hybrid thick film</li></ul>
<b>Main clients served</b>	<ul style="list-style-type: none"><li>▶ FIAT / GM Group</li><li>▶ VW</li><li>▶ DC</li><li>▶ BMW</li></ul>





# PLANTS DESCRIPTION

## Hortolandia (Brazil)

<b>Area</b>	31,000 m <sup>2</sup>
<b>Headcount</b>	
<b>Direct labour</b>	322
<b>Total</b>	535
<b>Certifications</b>	ISO 9000, ISO 14000, AVSQ94
<b>Products</b>	<ul style="list-style-type: none"><li>▶ Throttle bodies</li><li>▶ Intake manifolds</li><li>▶ Fuel rails</li><li>▶ Injectors</li><li>▶ Pressure regulators</li><li>▶ Oil pumps</li></ul>
<b>Technologies</b>	<ul style="list-style-type: none"><li>▶ Metal forming (die cast)</li><li>▶ Plastic (moulding)</li><li>▶ Precision machining</li><li>▶ Flexible assembly/test</li></ul>
<b>Main clients served</b>	<ul style="list-style-type: none"><li>▶ FIASA</li><li>▶ PSA</li><li>▶ RSA</li><li>▶ Volkswagen</li></ul>



# MAGNETIMARELLI POWERTRAIN IN SHANGHAI



**Company Established in March, 2000**

**1<sup>st</sup> Plant SOP in July 2000**

**Total Area: 25,000 m<sup>2</sup>**

**100% owned by Magneti Marelli Powertrain S.p.A.**

**1<sup>st</sup> phase Investment: \$ 30 million (Done)**

**Location: Shanghai Pudong Waigaoqiao Free Trade Zone**



# MM POWERTRAIN 2<sup>nd</sup> PLANT IN Wuhu



**2nd Plant SOP in Nov. 2003**

**Total Area: 25,000 m<sup>2</sup>**

**100% owned by Magneti Marelli  
Powertrain S.p.A.**

**2nd phase Investment: \$ 30 million**

**Location: Wuhu High-Tech. Industry  
Zone, with 4 hours Distance by vehicles  
away**



**MM POWERTRAIN  
PRODUCT PORTFOLIO  
&  
TECHNOLOGY ROAD  
MAP**



# 2003 : NEW MPI FLEX FUEL TECHNOLOGY

New FLEX FUEL systems can use  
free Alcool/Gasoline mix  
(Self-adaptive SW implementation)



## ACHIEVEMENT:

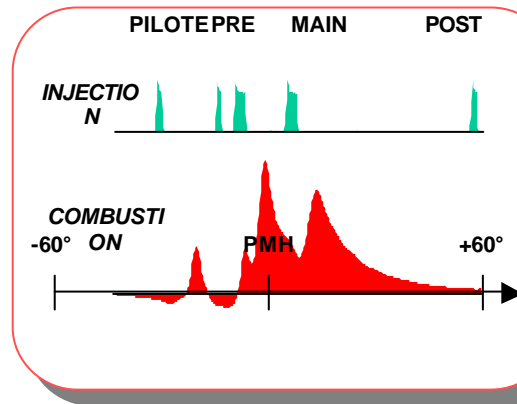
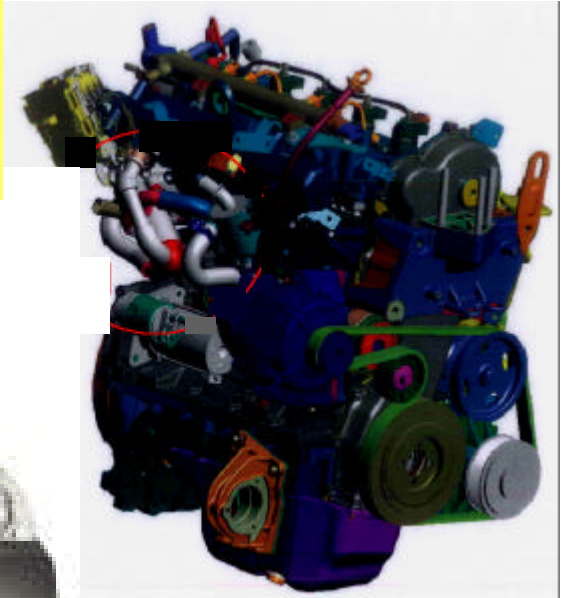
Record Market Share in Brasil (> 45% starting MY'05)  
through consolidation (FIAT – VW) and new awarded bid ( FORD )



# 2004 : DIESEL COMMON RAIL MULTIJET



**CRF-MM cooperation has produced a very innovative K.H. , instrumental to the evolution road map**



**ACHIEVEMENT:  
New FIAT 1,3lt Turbo Diesel Multijet Engine**



## MM leader in Automated Manual Transmission Market

	Ferrari/Maserati	360 - 550 Spyder-Coupé		
	Alfa Romeo	147-156		
	BMW	3/5/Z Series		
	Fiat	Punto-IDEA Panda-Y		
	RSA	Twingo-Clio SuperTwingo		
	PSA	N.Xsara N.Picasso-308		



# MAGNETI MARELLI SOLUTIONS

**FUEL  
ECONOMY**

**Engine Efficiency**

**Trasmission Eff.**

**Direct  
Fuel Inj**

**Diesel  
C.R.Multijet**

**Compress  
Natural Gas**

**Valve  
Control**

**Transmission  
Control**

**Hybrid  
Vehicle**



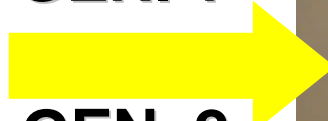
# GASOLINE DIRECT INJECTION

Injection Pressure:



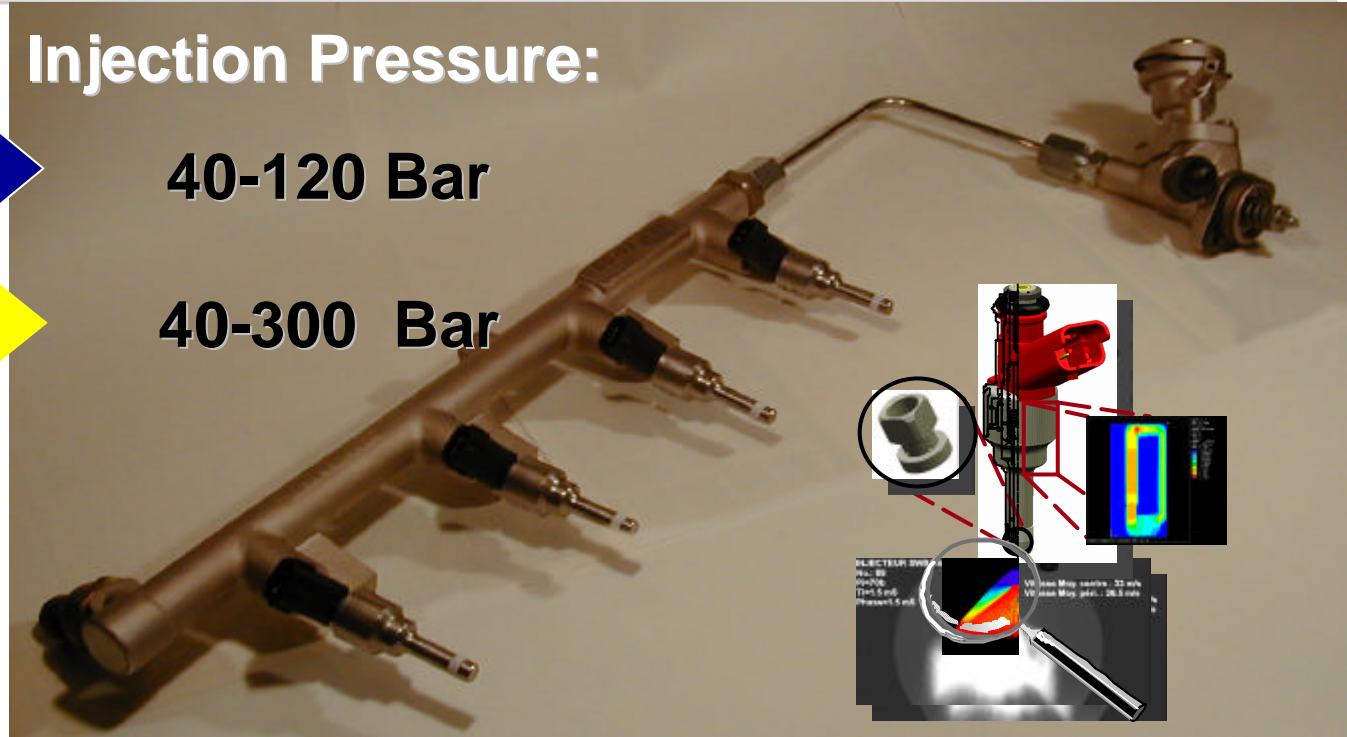
**GEN. 1**

40-120 Bar



**GEN. 2**

40-300 Bar



## Benefits

▶ Homo Stoichiometric



N.Aspirated Torque + 4/6%(F.e. 4/5)  
Turbo Downsizing F.economy 10/12%

▶ Stratified lean A/F 40-50



Fuel economy (CO2) 9/11%

1st awarded business VW : SOP 6/06



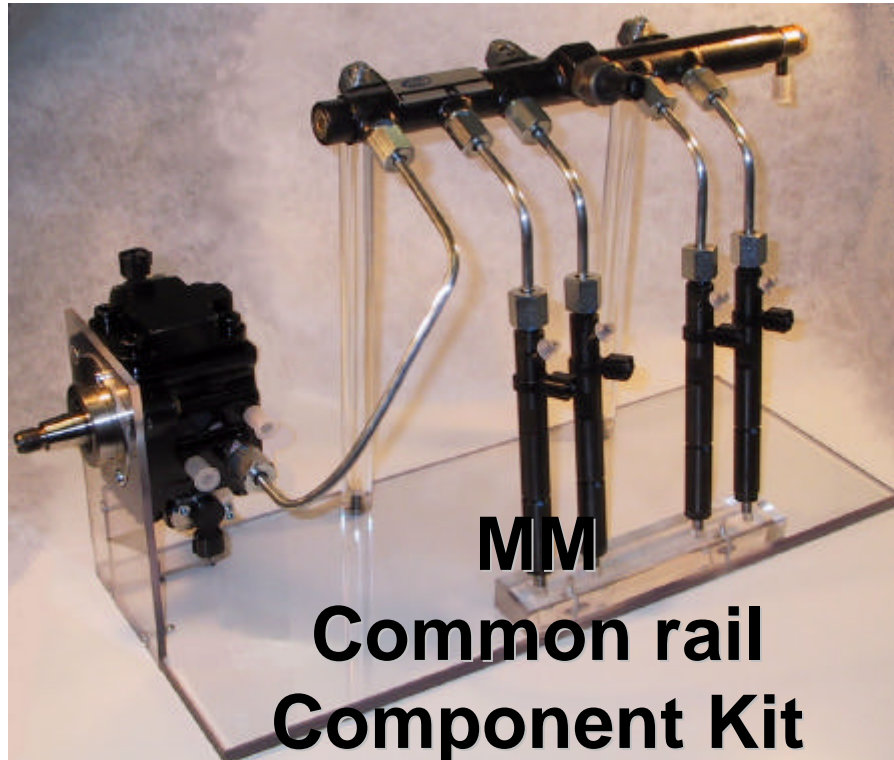
# DIESEL MULTIJET COMMON RAIL

**New Common Rail  
Multiple Injections (up to 7)**

## **Benefits**

**Benefits vs. current  
MULTIJET version:**

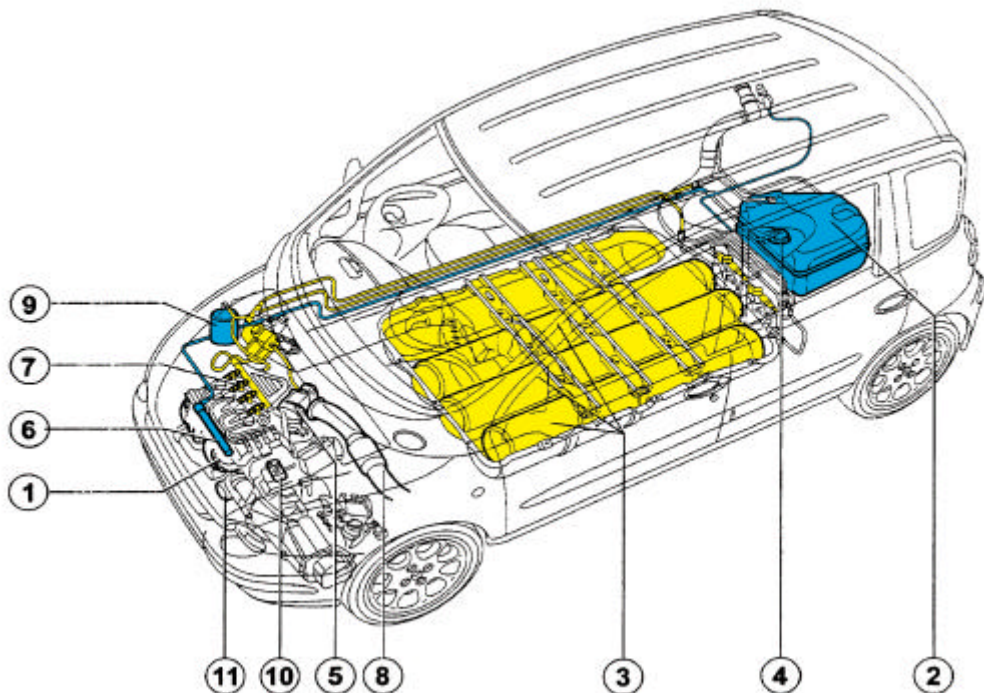
- ▶ **Emission reduction  
(Fullfill EURO 5 )**
- ▶ **Combustion noise  
improvement (especially  
in cold operation)**
- ▶ **Lower cost**



**Production on SDE : 2007**



# Compressed Natural Gas SYSTEMS



## Legenda

1. ENGINE N.A. or TURBO
2. GASOLINE TANK AND REIL
3. CNG TANK AND PIPES
4. GASOLINE PUMP
5. INTAKE MANIFOLD
6. GASOLINE RAIL
7. CNG RAIL
8. LAMBDA ON-OFF SENSOR
9. CANISTER SYSTEM
10. ENGINE COOLING
11. ENGINE OIL PUMP

## Benefits

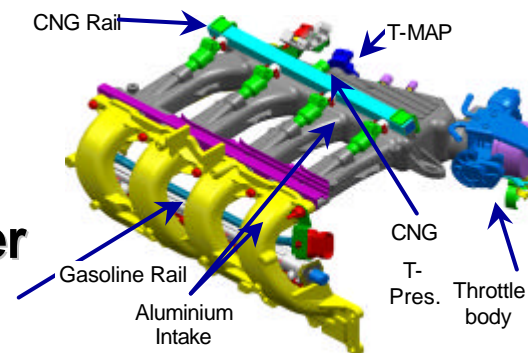
**Cost Advanteges for EndUser**

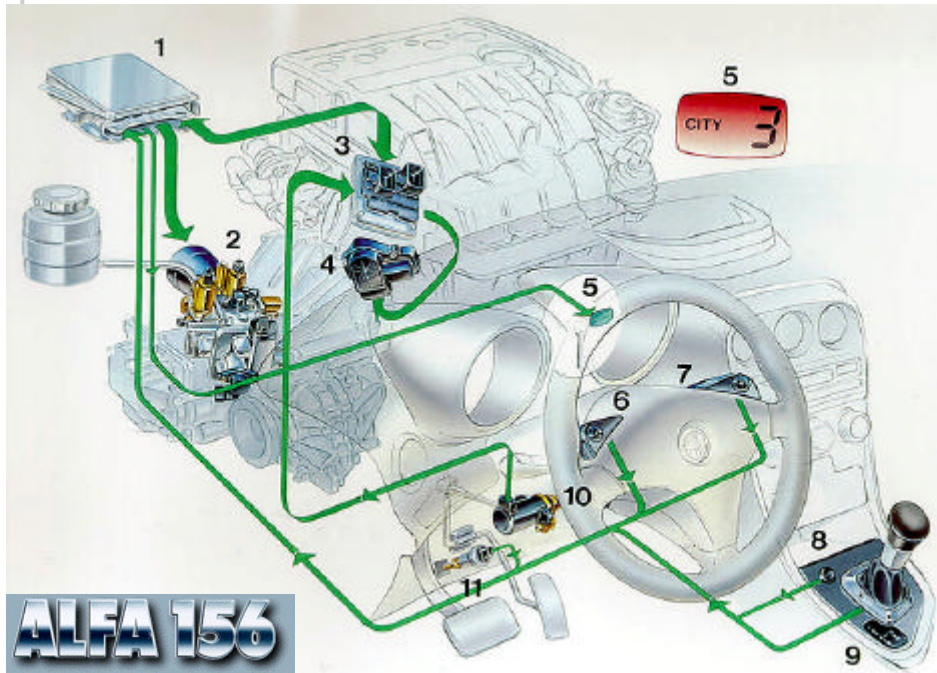
**Low CO<sup>2</sup> Emission (-30%)**

**Possibility to retrofit old car**

**Bifuel possibility**

**SOP :  
Q2/05**





- 1 → Transmission ECU
- 2 → Actuation group
- 3 → Engine ECU
- 4 → DBW
- 5 → Active shift display
- 6-7 → Up/Down buttons
- 8 → City mode button
- 9 → Up/Down lever
- 10 → Accelerator pedal position sensor
- 11 → Brake switch

## Benefits

Shorter time on change gear

Low weight

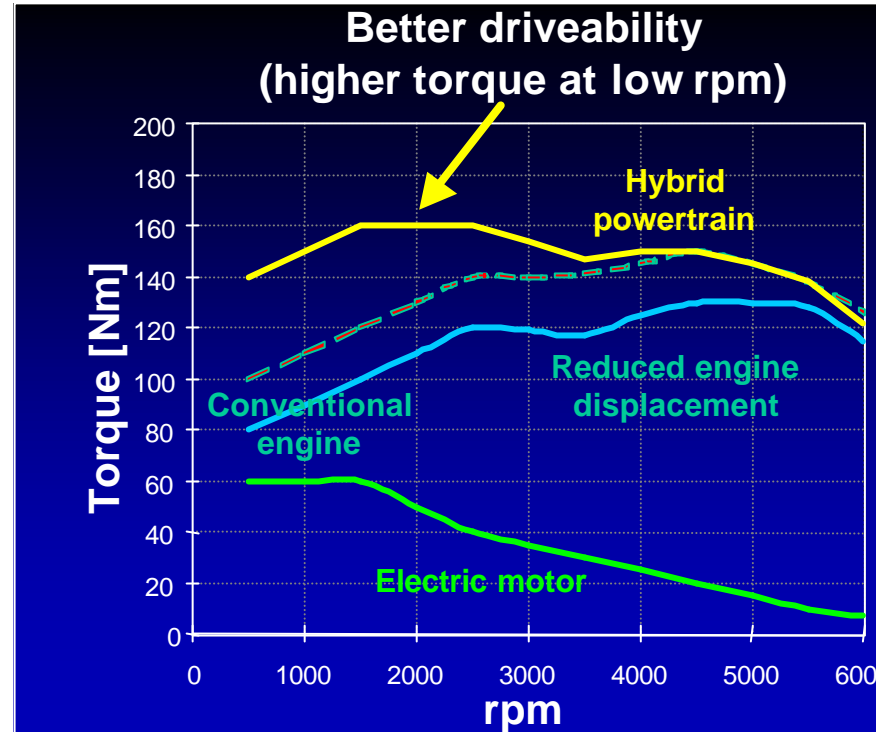
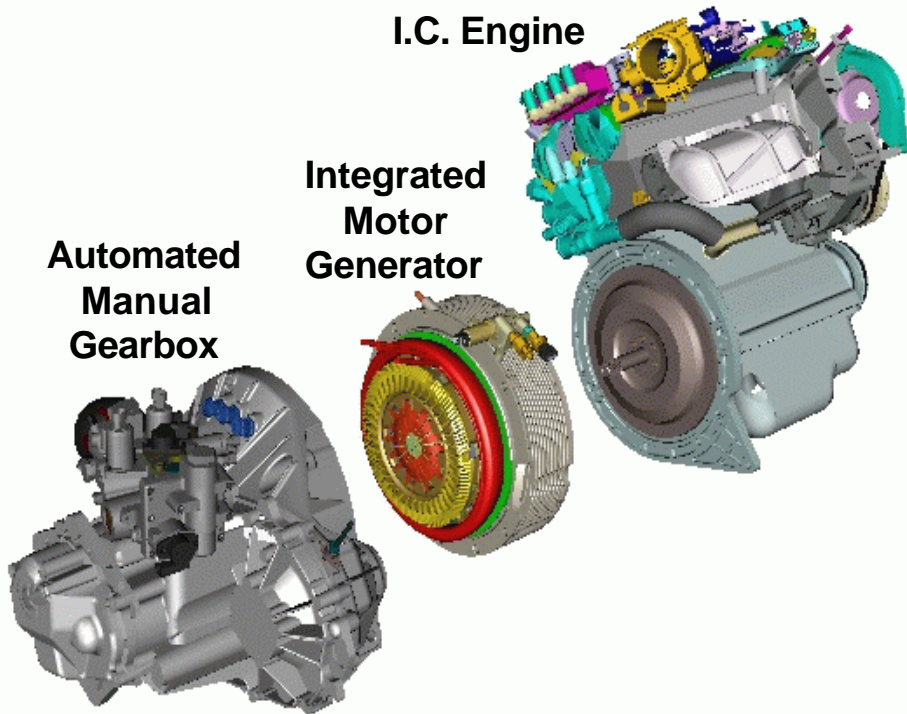
Automatic feature

Fuel economy

Gear box reliability



# MINIMAL HYBRID PWT SYSTEMS



## Functions

- ▶ High efficiency electrical generation (>80%)
- ▶ Quick and reliable engine cranking
- ▶ Stop & start
- ▶ Torque booster (+60Nm)
- ▶ Regenerative braking
- ▶ Minimal electric traction

**SOP : MY'07**

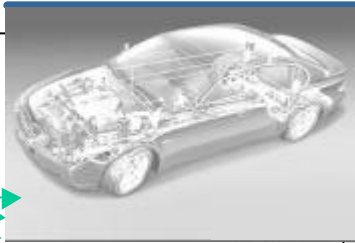
## Benefits

- ▶ Fuel economy: - 30%
- ▶ Reduced emissions: ULEV
- ▶ Better driveability:  
higher torque at low rpm



# Automotive Trends on System Development

OEM 1



Platform 1.1

Platform 1.2

Platform 1.n

OEM n



Platform m.1

Platform m.2

Platform m.n

**Higher reuse and exchangeability of SW**

**Exchangeability**  
between  
manufacturer's  
applications

e.g.: Diesel engine  
OEM 2

**management of highly integrated E/E**



Platform 2.1

Platform 2.2

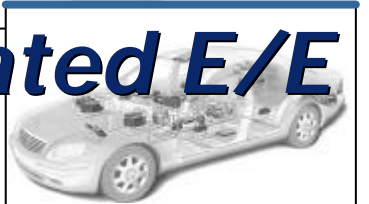
Platform 2.n

**Exchangeability**

supplier's  
solutions

e.g.: Car Multimedia System

OEM m



Platform m.1

Platform m.2

Platform m.n

**Exchangeability**  
**architectures.**

between  
vehicle  
platforms

e.g.: Transmission system

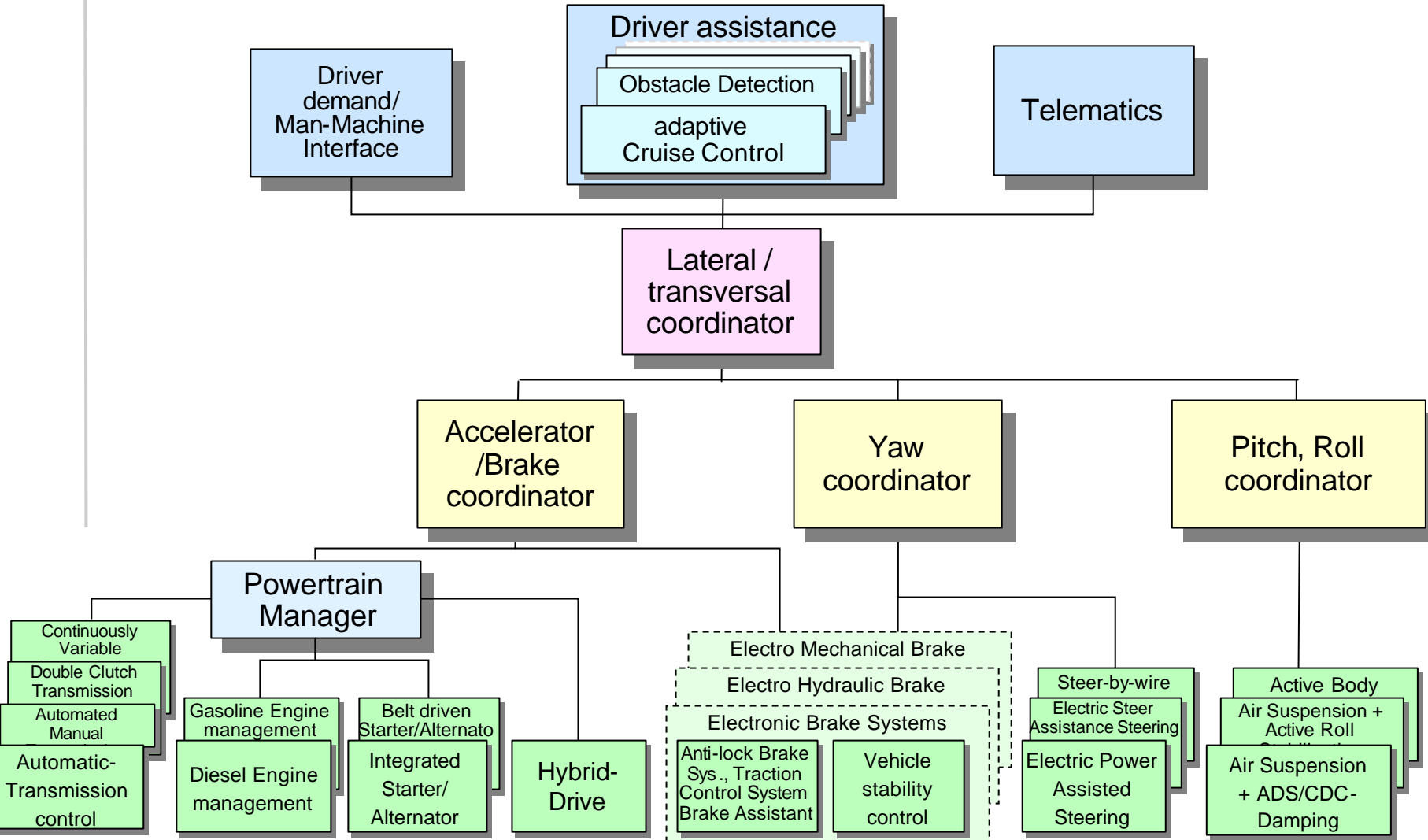


# AUTOSAR constellation

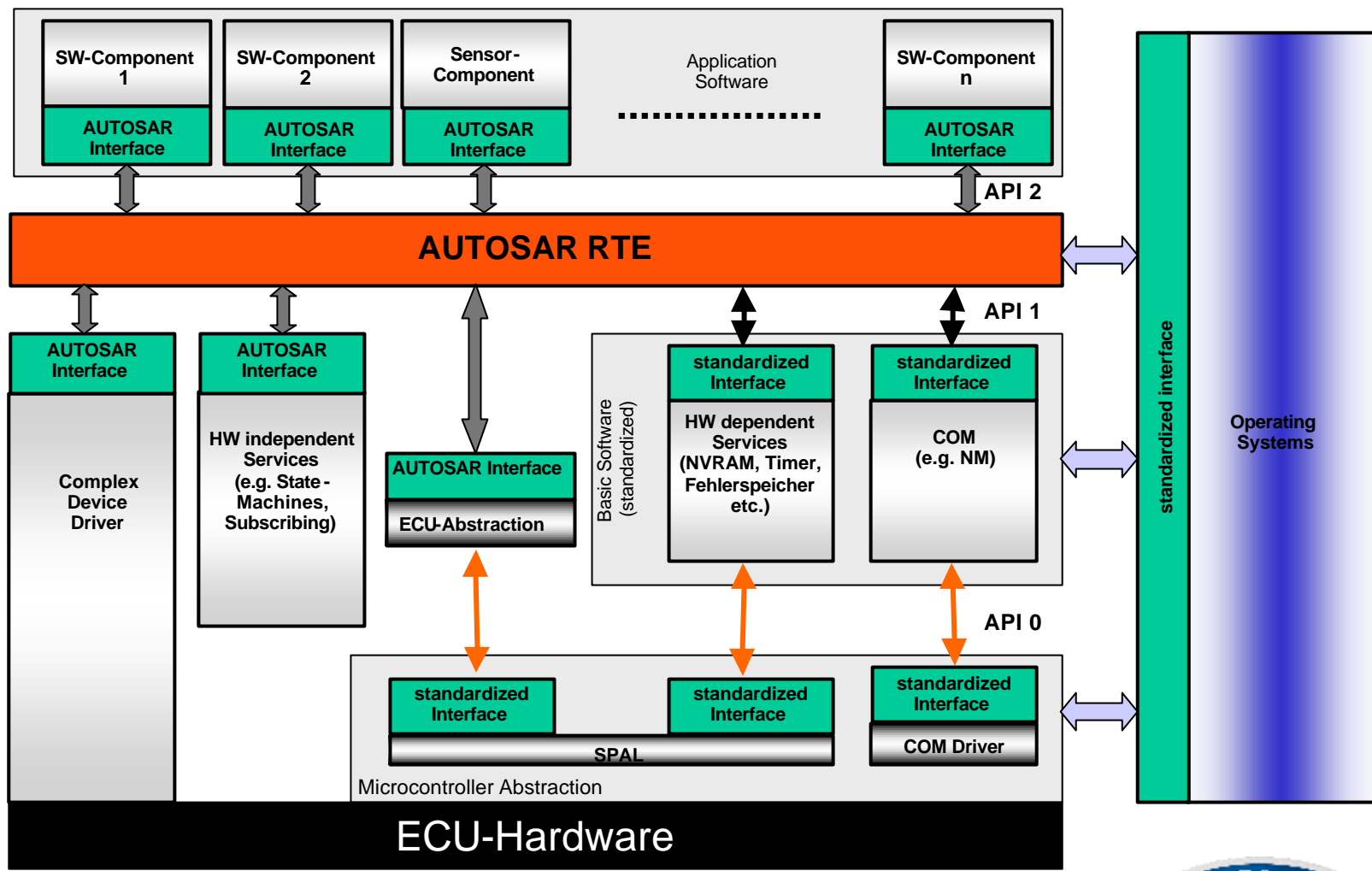




# Towards in car systems integration



# AUTOSAR Layered Architecture



# New Organization Outcome

SDC

BAS

Off the shelf development  
"bug free"



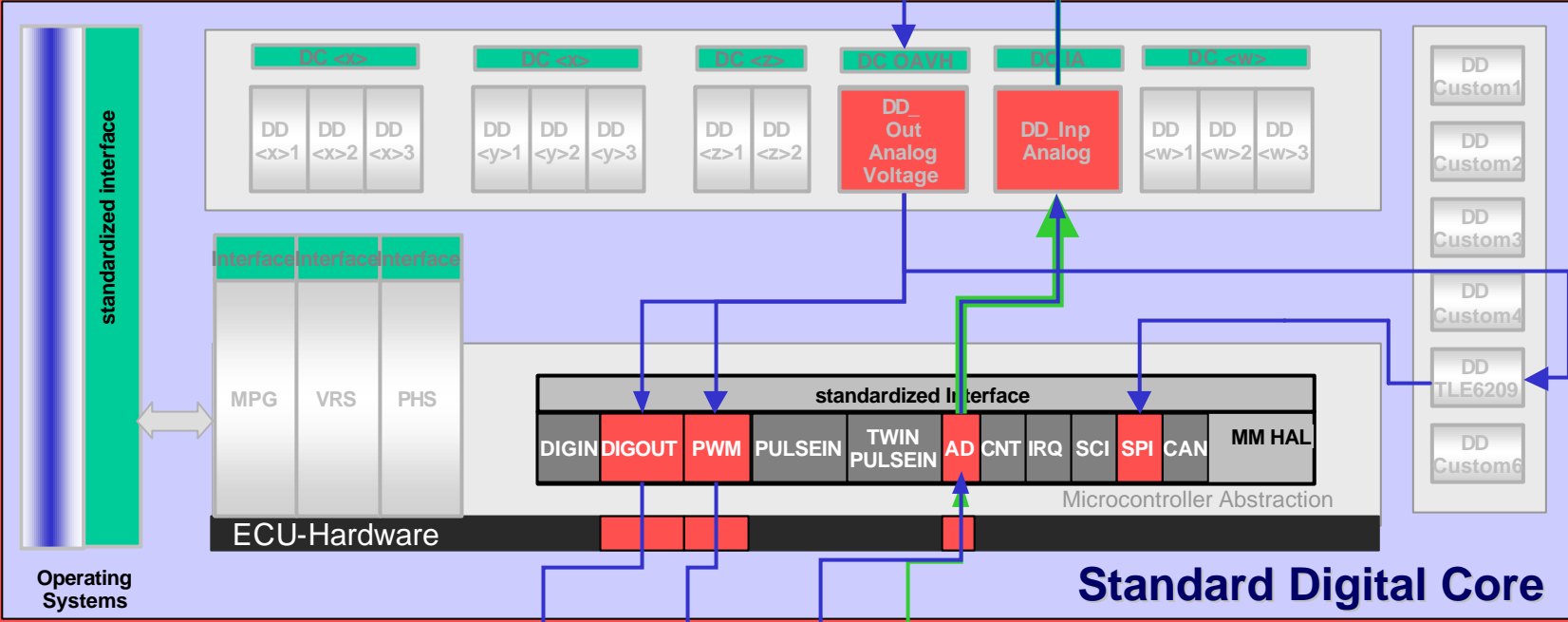
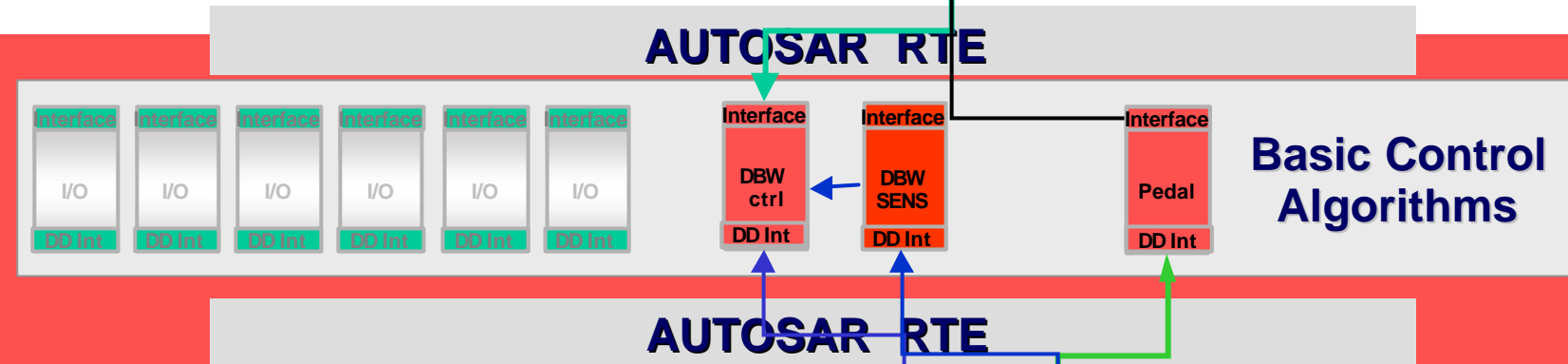
Sviluppo Sistema





**MAGNETI MARELLI**  
**CORE**

# Basic Application Software





**JRAUM & INNOVAZIONE**  
**Grandi tematiche per 2005**

**T6 - INNOVATION ( Ausiello sponsor)**

**Abate / Cristiani / Giorgetta / Marceca / Nesci / Reggiani / Rocchelli / Serra / Sola**

## Status as by Year 2004

La cooperazione  
era spezzettata in  
30 differenti  
contratti

13  
Dipartimenti  
Universitari  
coinvolti

La crescita dei rapporti con  
le università ha raggiunto  
anno dopo anno una  
dimensione di notevole  
impatto sul Budget della  
Powertrain

Budget 2004  
0,65 M€



# OBIETTIVI

**Razionalizzare la cooperazione con le UNIVERSITA'**

- Focus su RICERCA DI BASE e INNOVAZIONE

**Formare ed addestrare una generazione di nuovi tecnici destinati alla assunzione e alla integrazione in PWT mediante :**

- **MASTER in Ingegneria del Veicolo**

Progetti di sviluppo o di supporto basati sul concetto del " learning on the JOB" all'interno della azienda o della Università

**Fornire una "exchange area " tra tecnici della Marelli e docenti Universitari  
Dare spazio e supporto a progetti gestiti direttamente dalla università**





# **J RAUM**

**Raum in tedesco significa SPAZIO ,  
quindi**

**l'immagine che vogliamo formare è quella di uno  
spazio di Collaborazione tra M.Marelli e il sistema  
Università**



La organizzazione è basata su 5 Aree Disciplinari

- **4 di esse saranno collocate a Bologna,**  
INFORMATICA & CONTROLLI  
MATERIALI  
MECCANICA and MECCATRONICA  
FLUIDODINAMICA e TERMODINAMICA
- **L'area di progettazione HW sarà collocata a Venaria**

## JRAUM facilities

600 m2 nella palazzina centrale ( Officina 1 )

- JRAUM Badge daranno accesso ai locali e alle aree di lavoro previste

25 posti di lavoro con Working Station

Sale riunioni e studi per Visiting Professors

Auditorium per training and scambio di informazioni in azienda

Alcune Facilities saranno condivise ( 2 turni per Giorno )

- 2 Banchi Motori
- 2 Banchi prova Componenti
- 2 Banchi a rulli
- Laboratorio Chimico



# JRAUM COLLOCATION



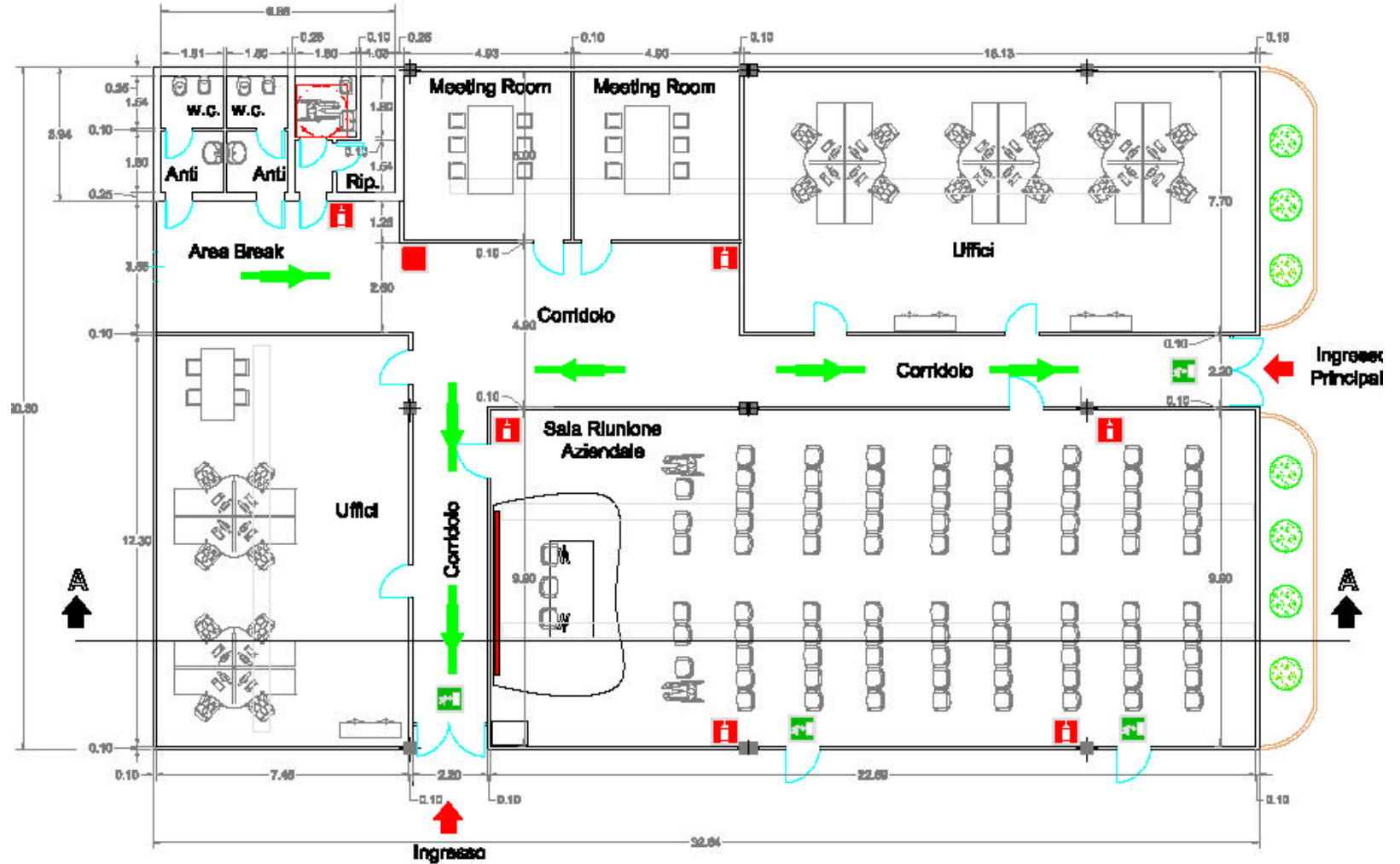
Banchi a rulli



Banchi Motore



# JRAUM Collocation

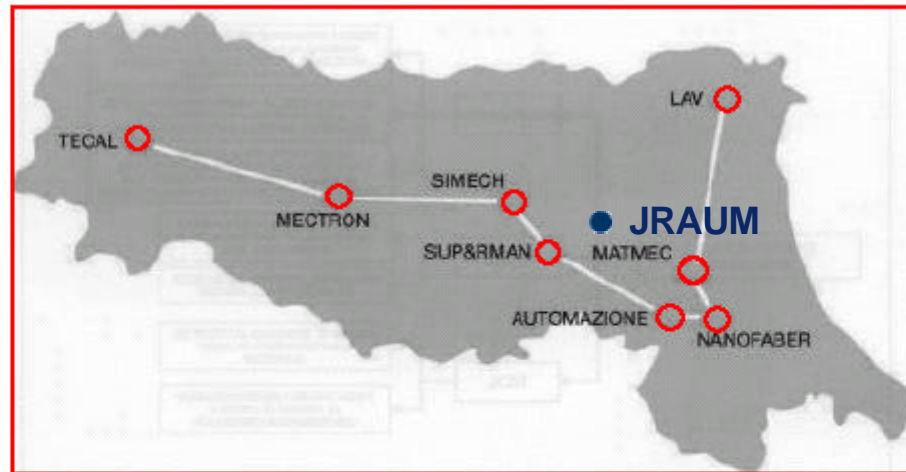


## JRAUM entra nel sistema HI-MECH

L'Emilia –Romagna si sta dotando di una rete di Laboratori nel settore della Meccanica e Meccatronica

La Società Consortile ASTER ( Regione + Università ) cui MM PWT si è associata nel 2004 è il punto di raccordo tra il LAB-NET e le industrie  
IL laboratorio JRAUM entra nella rete HI-MECH nei prossimi mesi

NET LAB



Si articolerà in **3 cluster** a partecipazione di soggetti Universitari e di soggetti industriali per rafforzare il sistema produttivo regionale con attività di ricerca applicata, di sviluppo precompetitivo e di innovazione finalizzate .

- 1) Sistemi Meccanici e Intelligenti,
- 2) Metodi Innovativi per l'Ingegneria Meccanica,
- 3) Materiali Nanostrutture e Superfici

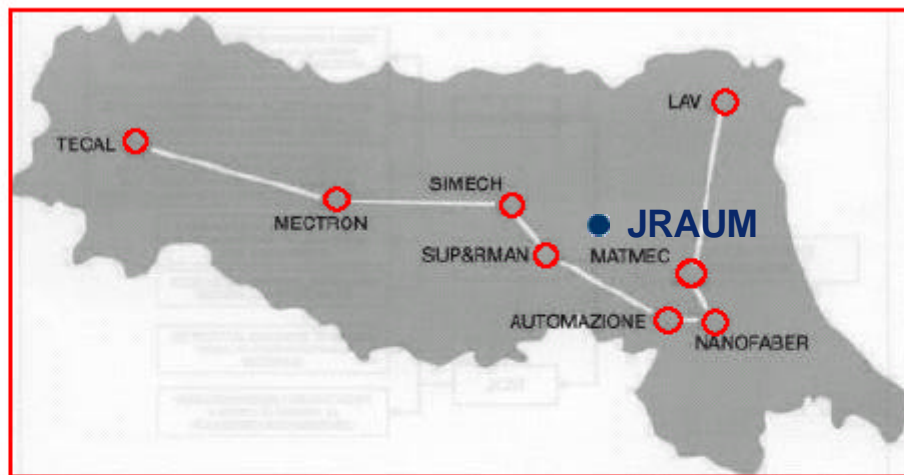


## JRAUM entra nel sistema HI-MECH

E' in corso il bando di finanziamento 2005 con fondi legati alla legge 297  
Tali Fondi saranno erogabili alle industrie collegate a LAB NET  
Complessivamente nel 2005 sono previste erogazioni di

- 25 M€ regionali ai NET LAB
- 25 M€ Ministeriali ( MIUR ) allocabili alle industrie Emiliane

NET LAB



Si articolerà in **3 cluster** a partecipazione di soggetti Universitari e di soggetti industriali per rafforzare il sistema produttivo regionale con attività di ricerca applicata, di sviluppo precompetitivo e di innovazione finalizzate .

- 1) Sistemi Meccanici e Intelligenti,
- 2) Metodi Innovativi per l'Ingegneria Meccanica,
- 3) Materiali Nanostrutture e Superfici



# TEMI INNOVAZIONE PER JRAUM

---

## **A ) MOTORI A BASSO IMPATTO AMBIENTALE**

Diesel EURO V

## **B) SVILUPPO VETTURE IBRIDE**

Powertrain ( Motore e Trasmissione)

## **C) SVILUPPO ECU GENERAZIONE 8**

Autosar compliant PWT system

## **D) FORMAZIONE RISORSE E TRAINING ON THE JOB**

Master

Dottorati







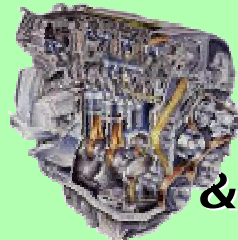
**Standard Digital Core (SDC)  
&  
**Basic Application Software (BAS)****

Basic Controls  
& Calibration

HAL Device  
Drivers

SDC

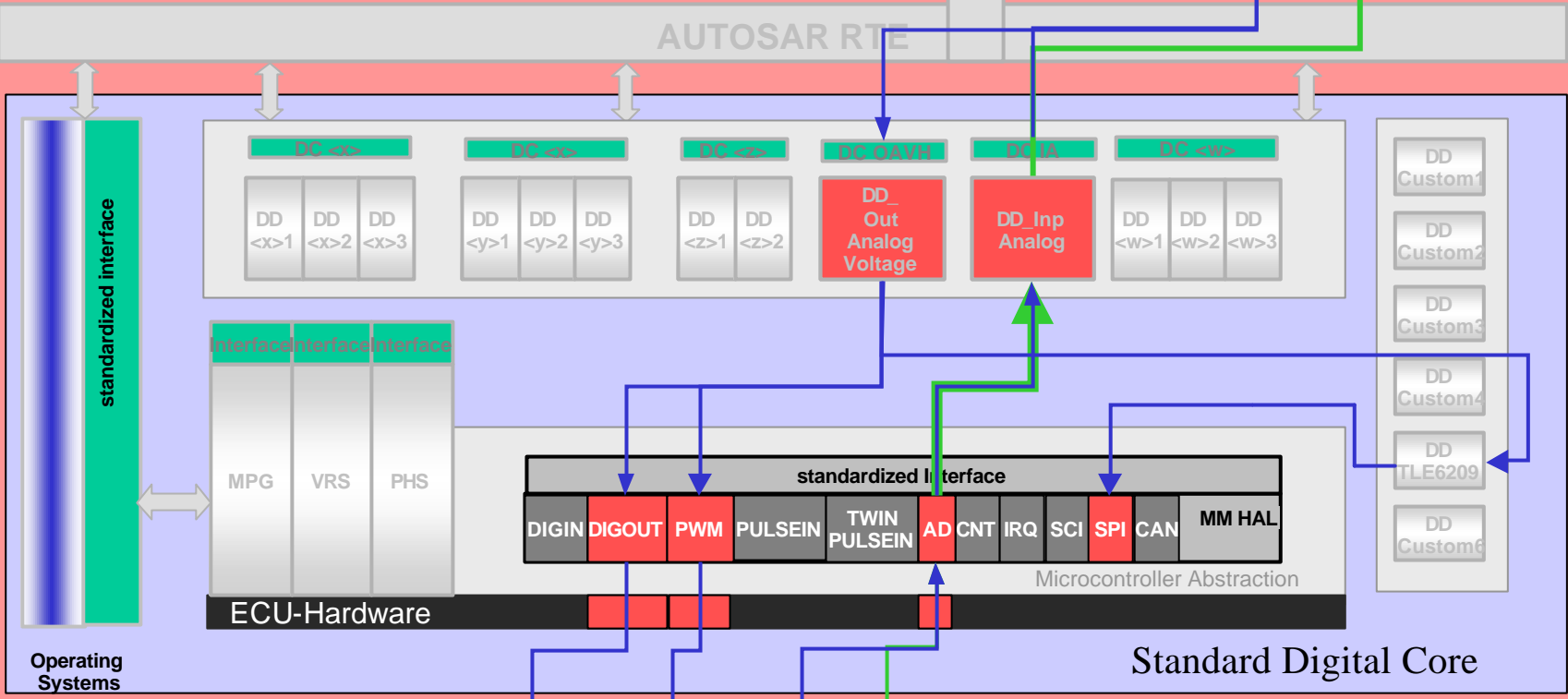
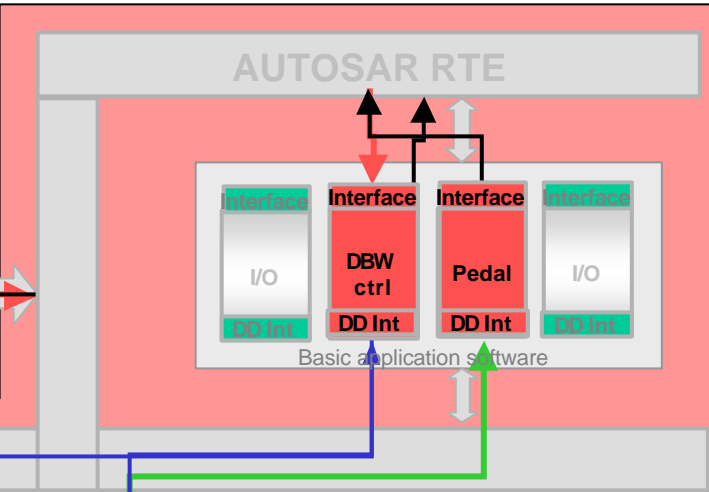
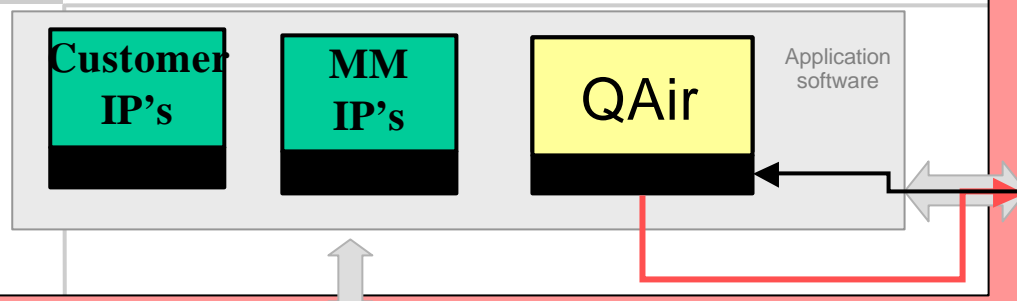
BAS



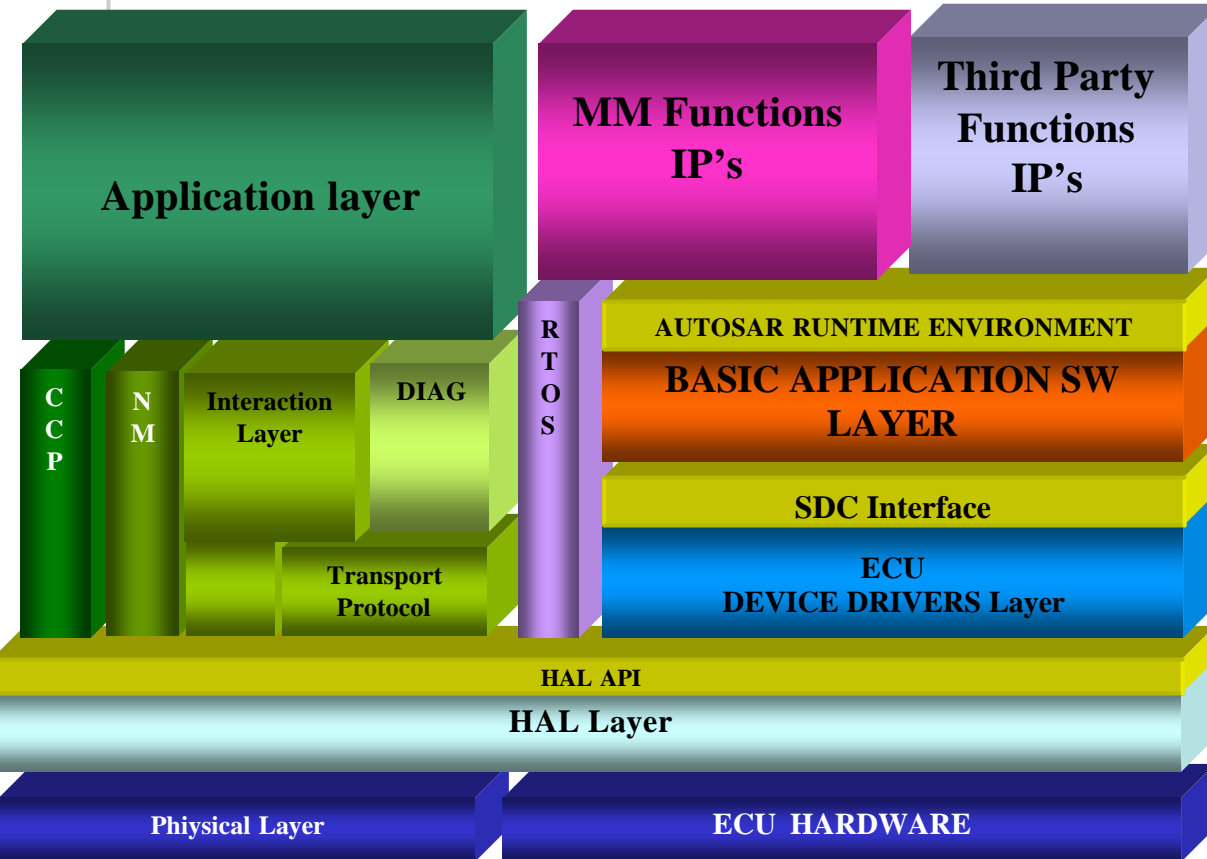
Ctm & MM PWT  
IP's Integration  
& In-Vehicle Tuning



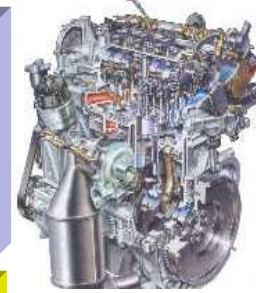
# Throttle Body Control



Extended Standard Digital Core



## Application Layer

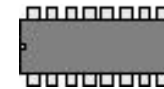


- Virtualizzazione del Plant (Motore, Trasmissione, assetto veicolo)
- Integrazione di IP's di terze parti

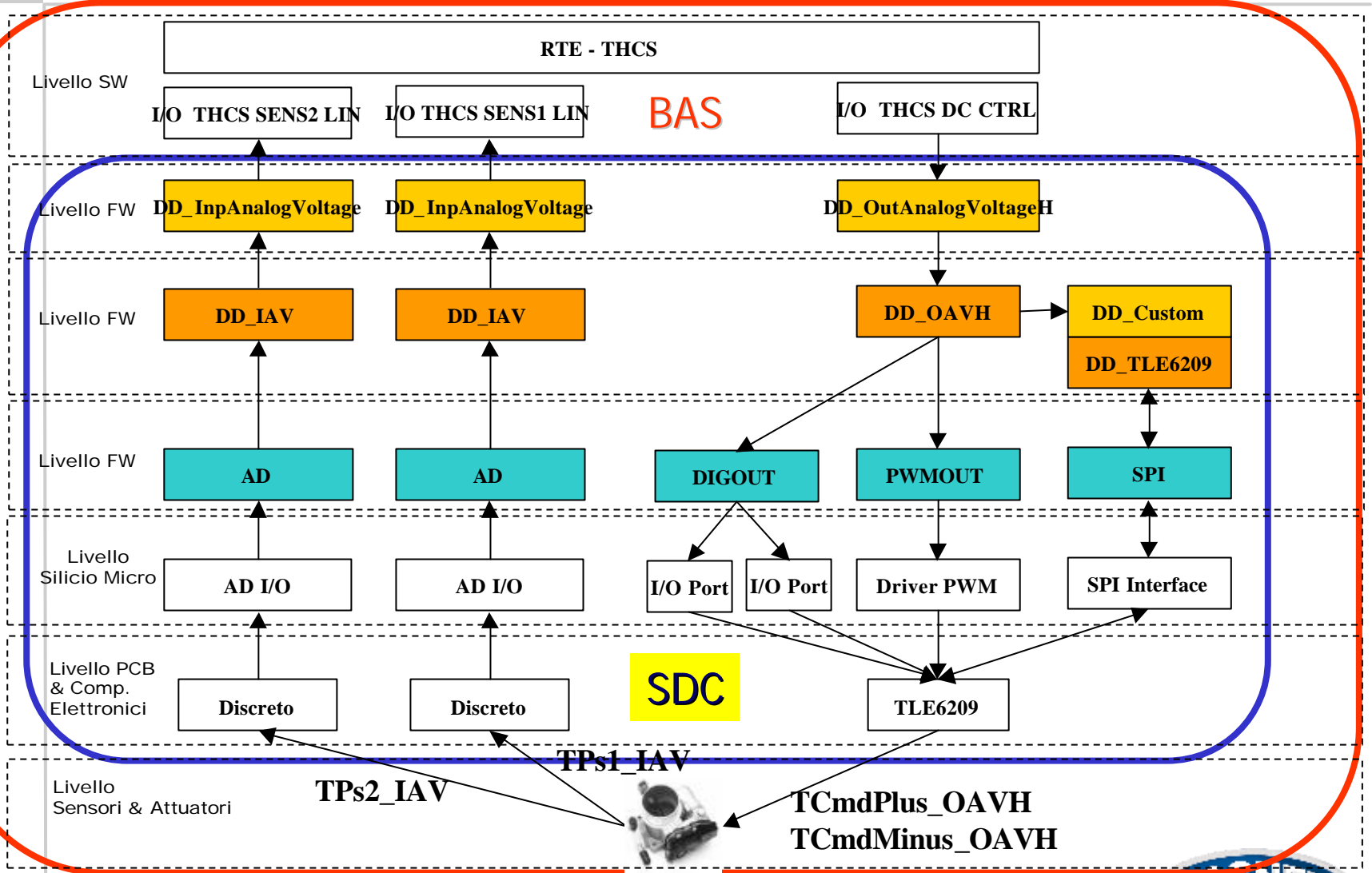
## BAS & SDC Layer



- Virtualizzazione sensori/attuatori
- Virtualizzazione dell'architettura elettronica
- Virtualizzazione del microcontrollore

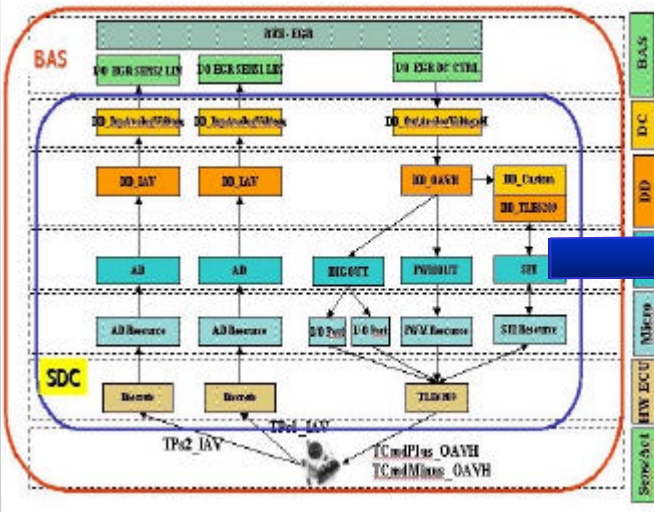


# Esempio: Controllo Corpo Farfallato



# Esempio: EGR con DC Motor 8DX – MJ2 Progettazione FIRMWARE

Cluster realizzativo



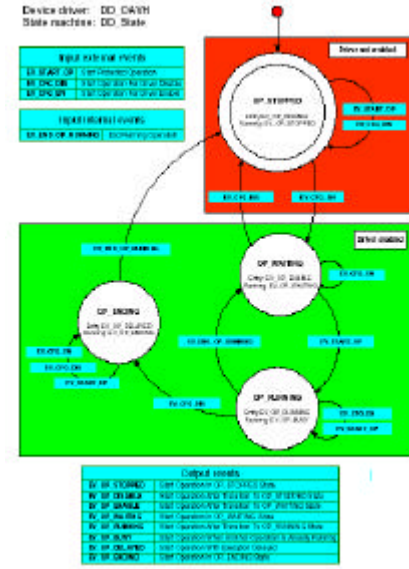
Device Driver: DD\_OAVH  
 Revision: 12  
 Revision comment: - Updated Micro Signal Qualifier  
 - Modified DD\_CtrlTask to use GetGpio to perform correct diagnosis and status with external pin 4 - 8bit

Device Class: DD\_OutAnalogVoltageH  
 Device Class Revision: 11

DIRS Drivers: **Micro signal qualifier:**  
 PFMOUT OAVH\_PFMOUT Output PFM signal  
 DSGOUT OAVH\_DSOUT Output DSGOUT DIR signal  
 OAVH\_DSERRUT OAVH\_DSERRUT Output DSGOUT DIR signal

Type: Oavar  
 Output: Vgts  
 Date: 07/03/06 17:31:23

Description:  
 Analog output voltage with 8-bits using a control PWM signal and a clock on signal (DIR). It is possible to disable the output with a digital DS signal. The electrical diagnosis is performed by a control.



```

Dynamic:
Description:
Operations:
Description:
    - Enable/disable the driver.
    The output is controlled by three signals: a pulse width modulation signal (PWM) and two digital input signals, one for direction (DIR) and one for output enable/disable (DIR).
    When the driver is disabled the output signal is programmed in three-state with the DIR control (DIR). The PWM and DIR signal must be disabled.
    When the driver is enabled the output signal is programmed at the duty cycle (DIR) and DIR signal, and the DIR signal is set to DIR_STOPPED (DIR).
    The DIR_STOPPED state configuration data specifies which is the electrical level of the output (DIR) signal required for each state.
    The DIR_STOPPED state configuration data specifies which is the electrical level of the output (DIR) signal required for each state.

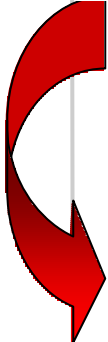
    /**
    /** SOURCE FILE NAME      DD_OAVH.C
    /** FUNCTION NAME        DD_OAVH_Except
    /** CREATION DATE       07/03/06
    /** SW WRITER           07/03/06
    /** UNIPHASE            - Exception management, request from the device driver at the end of command period,
    /** DESCRIPTION          used for diagnosis.*/
    **/
    void DD_OAVH_Except(c_DD_OutAnalogVoltageH *Obj)
    {
        /* Data Declaration Section */

        /* Data Init Section */
        c_DD_OAVH_PrivateData *PtrPrivateData = Obj->PrivateData;
        c_DD_OAVH_CfgStat *PtrCfgStat = Obj->CfgStat;

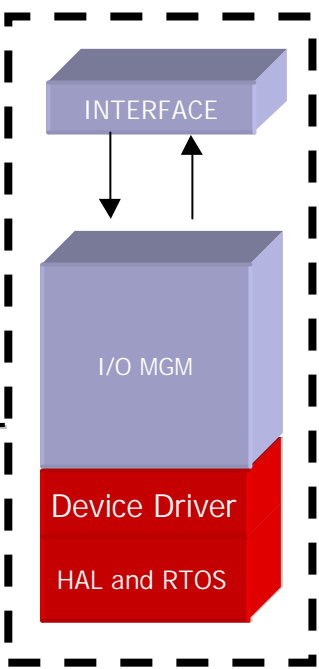
        /* Function body */
    }

    #ifdef DEBUG_ACTIVE
    void DD_OAVH_Debug(c_DD_OutAnalogVoltageH *Obj)
    {
        DebugData:
        PtrPrivateData = Obj->PrivateData;
        c_DD_OAVH_CfgStat *PtrCfgStat = Obj->CfgStat;

        DebugData.DD_Obj = (longword)Obj;
        DebugData.DD_State = (unsigned_word)PtrPrivateData->DD_State;
        DD_InternalDebug(4,DebugData);
    }
    
```

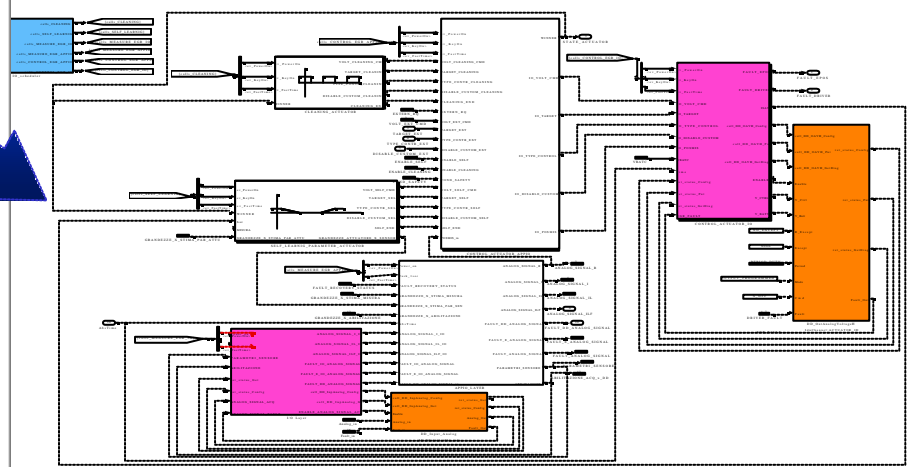
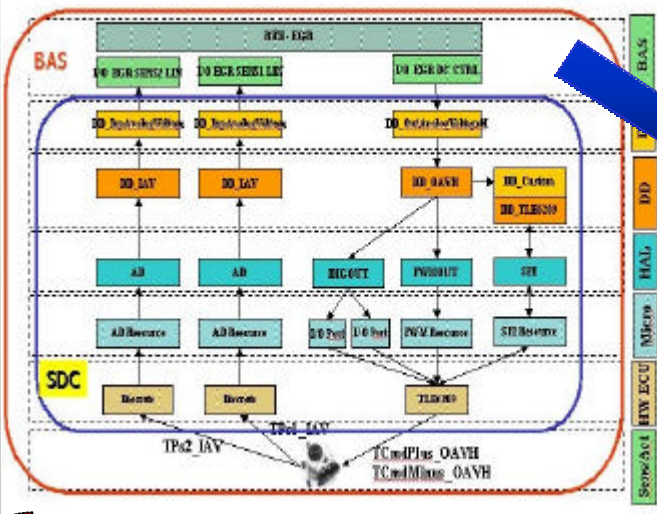


BAS Component



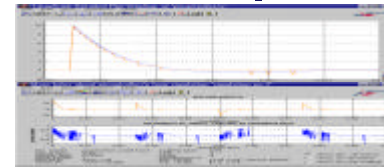
# Esempio: EGR con DC Motor 8DX – MJ2 Progettazione SOFTWARE

Cluster realizzativo



EGR Basic Control Algorithm

Target Link Autocode Environment



```
void integratutto4_initializer( void )
```

```
/* Initialize machine's broadcast event variable */
```

```
_sfEvent_ = CALL_EVENT;
```

```
_integratutto4MachineNumber_ =
```

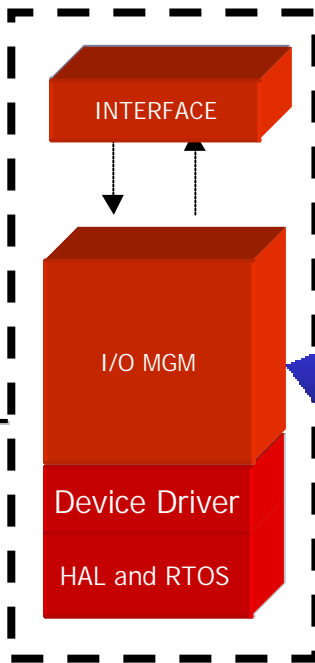
```
sf_debug_initialize_machine("integratutto4", "sfun", 0, 3, 0, 0, 0);
```

```
sf_debug_set_machine_event_thresholds(_integratutto4MachineNumber_, 0.0);
```

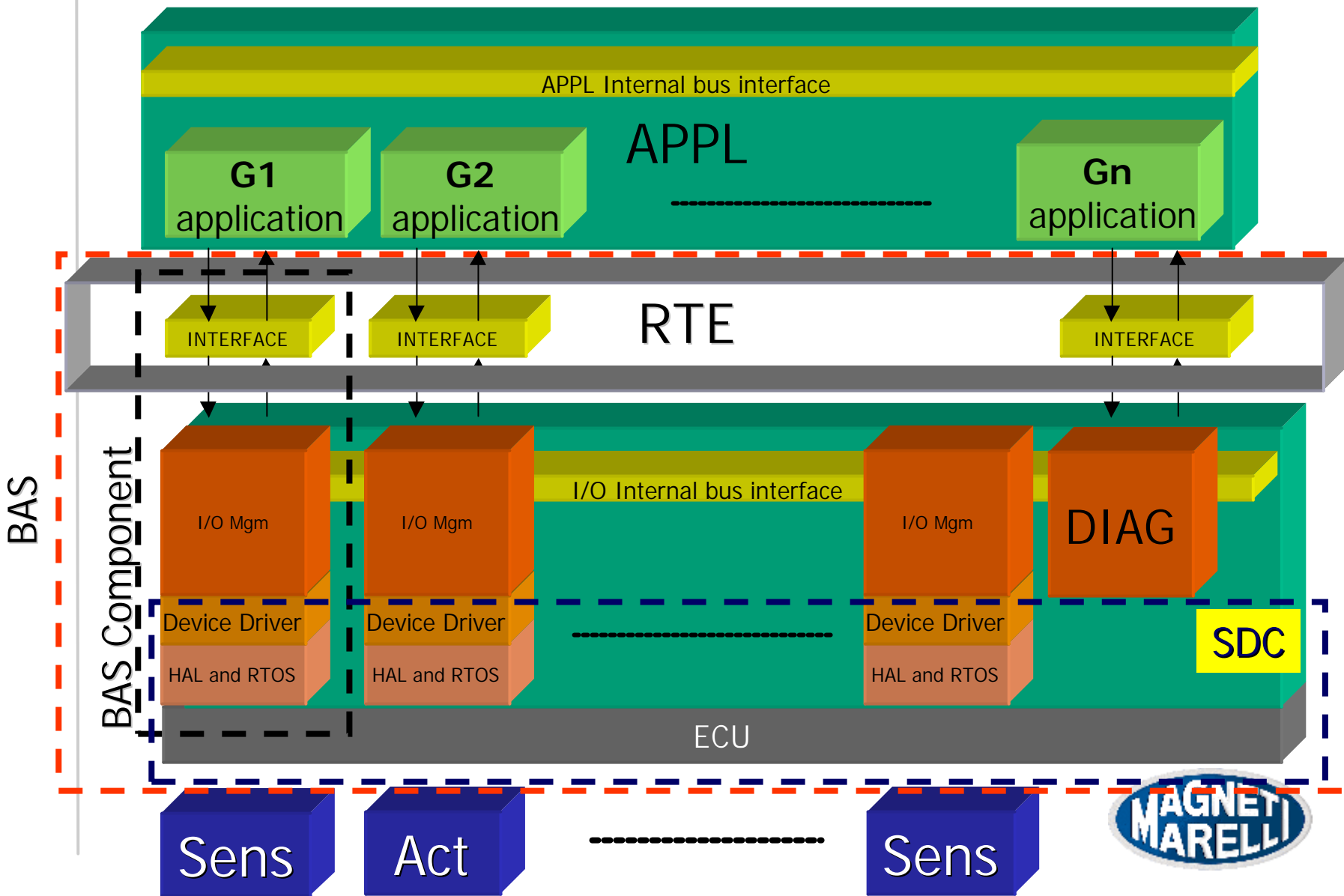
```
sf_debug_set_machine_data_thresholds(_integratutto4MachineNumber_, 0);
```

```
}
```

BAS Component



# INTEGRAZIONE BAS COMPONENTS - APPLICATIVO





### **“Esplorazione e sviluppo di soluzioni software, firmware e di configurazione prodotti informatici per applicazioni Powertrain su Piattaforme Elettroniche rispondenti ai requisiti AUTOSAR ”**

La ricerca verterà in particolare sui seguenti argomenti:

- Studio, partendo da algoritmi di controllo floating esistenti, di una metodologia di trasformazione che sia in grado di generare una rappresentazione intera che soddisfi le precisioni richieste e minimizzi l'utilizzo delle risorse di calcolo disponibili per un dato microcontrollore ;
- Analisi dei principali fornitori di ambienti di sviluppo dei protocolli di comunicazione (ETAS, VECTOR,...) per identificarne la copertura e l'applicabilità all'interno del ciclo di sviluppo del software Magneti Marelli sviluppando customizzazioni ed integrazioni mancanti
- Definizione dei pattern di test necessari per la verifica del prodotto SW integrato in ambiente di simulazione veicolo (HIL D\_Space) e sviluppo nell'ambiente nativo (linguaggio Python) dei pattern di test definiti
- Esplorazione, definizione ed utilizzo di linguaggi di specifica formali per la descrizione comportamentale, la simulazione ed il test di componenti firmware (HAL) ;
- Analisi, progetto e test dei componenti di comunicazione RTE definiti nell'ambito del Consorzio Internazionale AUTOSAR con particolare riguardo applicazioni Powertrain
- Esplorazione, studio ed integrazione o implementazione sistemi operativi embedded rispondenti agli standard automotive con particolare riferimento ad OSEK ed AUTOSAR

